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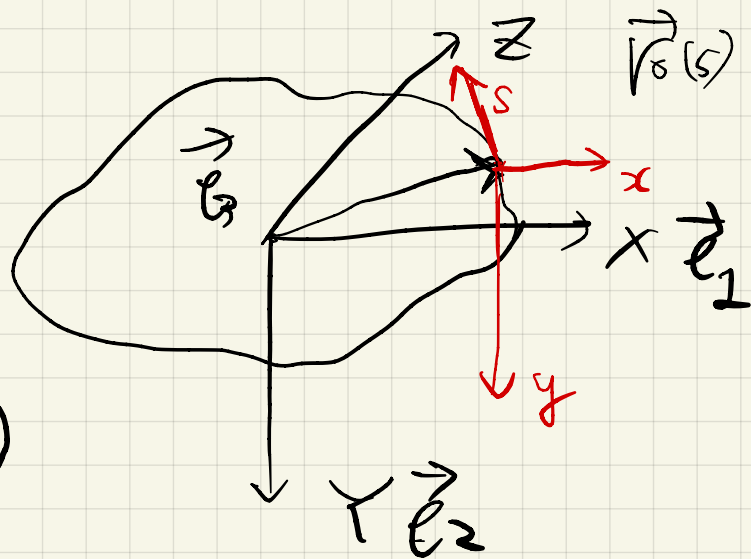
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# 座標変換



$$\dot{y} = 0$$

$$\vec{r}_0 = (X_0(s), 0, Z_0(s))$$

$$\hat{s} = (\dot{X}_0(s), 0, \dot{Z}_0(s))$$

$$\hat{\lambda} = (-\rho(s) \ddot{X}_0(s), 0, -\rho(s) \ddot{Z}_0(s))$$

$$\hat{\lambda} = \left( -\left( \frac{d\rho}{ds} \ddot{X}_0 + \rho \dddot{X}_0 \right), 0, \left( \frac{d\rho}{ds} \ddot{Z}_0 + \rho \dddot{Z}_0 \right) \right)$$

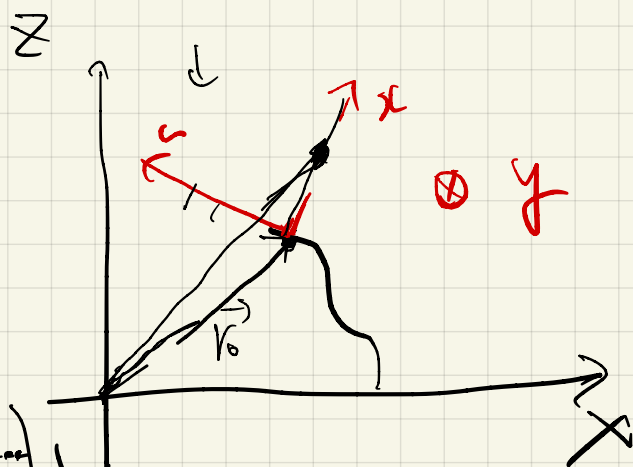
$$\hat{\lambda} \cdot \hat{\lambda} = \frac{1}{2} [(\hat{\lambda} \cdot \hat{\lambda})] = 0$$

$$\hat{s} \cdot \hat{\lambda} = -\hat{s} \cdot \hat{\lambda} = \frac{1}{\rho(s)} \quad (F)$$

$$\hat{y} \cdot \hat{\lambda} = 0 \quad (R \text{ 定})$$

$$\hat{\lambda} = \frac{1}{\rho(s)} \cdot \hat{s}(s)$$

$$= \left( \frac{\dot{X}_0}{\rho(s)}, 0, \frac{\dot{Z}_0}{\rho(s)} \right)$$



$$(\vec{r} - \vec{r}_0) \cdot \hat{s} = 0$$

$$\dot{X}_0(X - X_0) + \dot{Z}_0(Z - Z_0) = 0$$

基底基底 ( $\vec{e}_1, \vec{e}_2, \vec{e}_3$ )  $\rightarrow$  ( $\hat{x}, \hat{y}, \hat{s}$ )

変換規則

$$\hat{x} = -\rho(s) (\ddot{x}_0 \vec{e}_1 + \ddot{z}_0 \vec{e}_3) \quad \hat{y} = \vec{e}_2$$

$$\hat{s} = \dot{x}_0 \vec{e}_1 + \dot{z}_0 \vec{e}_3$$

$$\vec{e}_1 = \frac{\dot{z} \hat{x} + \rho \dot{z}_0 \hat{s}}{\rho (\dot{z}_0 \dot{x}_0 - \dot{z}_0 \ddot{x}_0)}$$

$$\vec{e}_3 = \frac{\dot{x}_0 \hat{x} + \rho \ddot{x}_0 \hat{s}}{\rho (\ddot{x}_0 \dot{z}_0 - \dot{x}_0 \ddot{z}_0)} = - \frac{\dot{x}_0 \hat{x} + \rho \ddot{x}_0 \hat{s}}{\rho (\dot{z}_0 \dot{x}_0 - \dot{z}_0 \ddot{x}_0)}$$

$$\vec{e}_2 = \hat{y}$$

$\vec{A}$  の成分の変換規則は

$$\vec{A} = A_x \hat{x} + A_y \hat{y} + A_s \hat{s}$$

$$= (-\rho(s) \dot{x}_0 A_x + \dot{x}_0 A_s) \vec{e}_1 + A_y \vec{e}_2$$

$$+ (-\rho(s) \dot{z}_0 A_x + \dot{z}_0 A_s) \vec{e}_3$$

$$= A_1 \vec{e}_1 + A_2 \vec{e}_2 + A_3 \vec{e}_3$$

$$A_1 = (-\rho(s) \ddot{x}_0 A_x + \dot{x}_0 A_s)$$

$$A_2 = A_y$$

$$A_3 = (-\rho(s) \ddot{z}_0 A_z + \dot{z}_0 A_s)$$

微分  
 $\frac{d}{ds} \frac{1}{\rho}$

$$\frac{\partial F(x, y, z)}{\partial x} = \frac{\partial F}{\partial x} \frac{\partial x}{\partial X} + \frac{\partial F}{\partial y} \frac{\partial y}{\partial X} + \frac{\partial F}{\partial s} \frac{\partial s}{\partial X}$$

$$x = x(X, z) \quad y = Y \quad s = s(x, z)$$

$z = z(z)$

$$\vec{r} = \vec{r}_0 + x \hat{x} + y \hat{y} + z \hat{z}$$

$$X = X_0 - \rho(s) \cdot x \ddot{X}_0$$

$$Z = z_0 - \rho(s) \cdot z \ddot{Z}_0$$

$$-\rho \left[ (x - X_0) \ddot{X}_0 + (z - z_0) \ddot{Z}_0 \right] = \rho x \left( \ddot{X}_0 + \ddot{Z}_0 \right) = x$$

$$\left( \frac{1}{\rho} \right)^2 \hat{x} \cdot \hat{x}$$

↓

$$\frac{\partial x}{\partial x} = -\rho \frac{\partial s}{\partial x} [(x-x_0)\ddot{x}_0 + (z-z_0)\ddot{z}_0]$$

$$- \rho \left[ \left(1 - \dot{x}_0 \frac{\partial s}{\partial x}\right) \ddot{x}_0 + (x-x_0) \ddot{x}_0 \frac{\partial s}{\partial x} - \dot{z}_0 \frac{\partial s}{\partial x} \ddot{z}_0 + (z-z_0) \ddot{z}_0 \frac{\partial s}{\partial x} \right]$$

$$= -\rho \ddot{x}_0 + \rho \frac{\partial s}{\partial x} (\ddot{x}_0 \dot{x}_0 + \ddot{z}_0 \dot{z}_0) - \frac{\partial s}{\partial x} (\rho \ddot{x}_0 + \rho \dot{x}_0) (x-x_0) + (\rho \ddot{z}_0 + \rho \dot{z}_0) (z-z_0)$$

$$= -\rho \ddot{x}_0 + \frac{\partial s}{\partial x} \left( \frac{\dot{x}_0}{\rho(s)} (x-x_0) + \frac{\dot{z}_0}{\rho(s)} (z-z_0) \right) \rightarrow 0$$

$$= -\rho \ddot{x}_0$$

$$\ddot{x}_0 \dot{x}_0 + \ddot{z}_0 \dot{z}_0 = -\frac{1}{\rho(s)} \hat{s} \cdot \hat{x} = 0$$

同様にして

$$\frac{\partial x}{\partial z} = -\rho \ddot{x}_0$$

$s = s(x, z)$   $x, z$   
→ 微分  
 $\dot{x}_0(x - x_0) + \dot{z}_0(z - z_0) = 0$

$$\ddot{x}_0 \frac{\partial s}{\partial x} (x - x_0) + \dot{x}_0 \left( 1 - \frac{\partial s}{\partial x} \dot{x}_0 \right) + \ddot{z}_0 \frac{\partial s}{\partial z} (z - z_0) - \dot{z}_0 \dot{z}_0 \frac{\partial s}{\partial z} = 0$$

$$\frac{\partial s}{\partial x} \left( \underbrace{\ddot{x}_0(x - x_0) + \ddot{z}_0(z - z_0)}_{-\frac{x}{\rho}} - \underbrace{(\dot{x}_0^2 + \dot{z}_0^2)}_1 \right) = -\dot{x}_0$$

$$\frac{\partial s}{\partial x} = \frac{\dot{x}_0}{1 + \frac{x}{\rho}}$$

同様  $\frac{\partial s}{\partial z} = \frac{\dot{z}_0}{1 + \frac{x}{\rho}}$

また

$$\frac{\partial x}{\partial x} = -\rho \dot{x}_0 \frac{\partial x}{\partial y} = 0 \quad \frac{\partial x}{\partial z} = -\rho \dot{z}_0$$

$$\frac{\partial y}{\partial x} = 0 \quad \frac{\partial y}{\partial y} = 1 \quad \frac{\partial y}{\partial z} = 0$$

$$\frac{\partial s}{\partial x} = \frac{\dot{x}_0}{1 + \frac{x}{\rho}} \quad \frac{\partial s}{\partial y} = 0 \quad \frac{\partial s}{\partial z} = \frac{\dot{z}_0}{1 + \frac{x}{\rho}}$$

二つの電位を2次元で使うから

$$\left( \frac{\partial A_3}{\partial y} - \frac{\partial A_2}{\partial z} \right) \vec{e}_1 = (\text{rot } \vec{A})_x$$

$$= \left( \frac{\partial}{\partial y} (-\rho \ddot{z}_0 A_x + \dot{z}_0 A_s) - \frac{\partial}{\partial z} A_y \right) \left( \frac{\dot{z}_0 \hat{x} + \rho \ddot{z}_0 \hat{s}}{\rho (\dot{z}_0 \dot{x}_0 - \dot{z}_0 \ddot{x}_0)} \right)$$

$$= \left( \rho \ddot{z}_0 \frac{\partial A_x}{\partial y} + \dot{z}_0 \frac{\partial A_s}{\partial y} - \frac{\partial A_y}{\partial z} (-\dot{z}_0) - \frac{\partial A_y}{\partial s} \frac{\dot{z}_0}{(1 + \frac{x}{\rho})} \right) \square$$

$$\left( \frac{\partial A_1}{\partial z} - \frac{\partial A_3}{\partial x} \right) \vec{e}_2 = (\text{rot } \vec{A})_y$$

$$\left[ \begin{aligned} & \left( -\rho \ddot{x}_0 A_x - \rho(s) \ddot{x}_0 \right) \frac{\dot{z}_0}{1 + \frac{x}{\rho}} - \rho(s) \ddot{x}_0 \left( \frac{\partial A_x}{\partial x} (-\rho \ddot{z}) + \frac{\partial A_x}{\partial s} \frac{\dot{z}_0}{1 + \frac{x}{\rho}} \right) \\ & + \dot{x}_0 \frac{\ddot{z}_0}{1 + \frac{x}{\rho}} A_s + \dot{x}_0 \left( \frac{\partial A_s}{\partial x} (-\rho \ddot{z}_0) + \frac{\partial A_s}{\partial s} \frac{\dot{z}_0}{1 + \frac{x}{\rho}} \right) \\ & - \left( \rho \ddot{z}_0 A_x - \rho(s) \ddot{z}_0 A_x \right) \frac{\dot{x}_0}{1 + \frac{x}{\rho}} - \rho(s) \ddot{z}_0 \left( \frac{\partial A_x}{\partial x} (-\rho \ddot{x}_0) + \frac{\partial A_x}{\partial s} \frac{\dot{x}_0}{1 + \frac{x}{\rho}} \right) \end{aligned} \right]$$

$$\frac{\ddot{x}}{\rho} = -\ddot{x} - \rho(s)\ddot{y} \quad \text{for } \epsilon \ll \rho \text{ use}$$

$$= -\rho \frac{1}{\left(1 + \frac{x}{\rho}\right)} (\ddot{x}_0 \dot{z}_0 - \dot{x}_0 \ddot{z}_0) \frac{\partial A_x}{\partial s}$$

$$+ (\ddot{x}_0 \dot{z}_0 - \dot{x}_0 \ddot{z}_0) \frac{1}{1 + \frac{x}{\rho}} A_s$$

$$+ \rho (\ddot{x}_0 \dot{z}_0 - \dot{x}_0 \ddot{z}_0) \frac{\partial A_s}{\partial x}$$

$$\left[ \begin{aligned} & \ddot{x}_0 \dot{z}_0 - \dot{x}_0 \ddot{z}_0 \\ & \frac{\hat{x}}{\rho(s)} \times \hat{s} = \frac{\hat{y}}{\rho(s)} = (\ddot{x}_0, 0, \ddot{z}_0) \times (\dot{x}_0, 0, \dot{z}_0) \\ & = (0, \dot{z}_0 \ddot{x}_0 - \dot{x}_0 \ddot{z}_0, 0) = \left(0, \frac{1}{\rho}, 0\right) \\ & \ddot{x}_0 \dot{z}_0 - \dot{x}_0 \ddot{z}_0 = -\frac{1}{\rho} \end{aligned} \right.$$

$$\left( \frac{\partial A_r}{\partial z} - \frac{\partial A_z}{\partial x} \right) \hat{z} = \left( \frac{1}{1 + \frac{x}{\rho}} \frac{\partial A_s}{\partial s} - \frac{A_s}{\rho \left(1 + \frac{x}{\rho}\right)} \right)$$

$$= \frac{1}{1 + \frac{x}{\rho}} \left( \frac{\partial A_r}{\partial s} - \frac{\partial \left[ \left(1 + \frac{x}{\rho}\right) A_s \right]}{\partial x} \right) \hat{y}$$



$$\left( \frac{\partial A_2}{\partial x} - \frac{\partial A_1}{\partial y} \right) \vec{e}_3$$

$$= \left( \frac{\dot{x}}{1 + \frac{x}{\rho}} \frac{\partial A_g}{\partial s} - \rho \ddot{x} \frac{\partial A_g}{\partial x} + \rho \ddot{x}_0 \frac{\partial A_x}{\partial y} - \dot{x}_0 \frac{\partial A_s}{\partial y} \right) \left( -\dot{x} \hat{x} + \rho \dot{x}_0 \hat{s} \right)$$

$$\left( \frac{\partial A_3}{\partial y} - \frac{\partial A_2}{\partial z} \right) \vec{e}_2 + \left( \frac{\partial A_1}{\partial x} - \frac{\partial A_1}{\partial y} \right) \vec{e}_3$$

$$= \hat{x} \left[ \frac{\partial A_g}{\partial s} \left( \frac{\dot{x}_0^2 - \dot{z}_0^2}{1 + \frac{x}{\rho}} \right) + \frac{\partial A_s}{\partial y} \right]$$

$$\hat{s} \left( \frac{\partial A_g}{\partial x} - \frac{\partial A_x}{\partial y} \right)$$

$$= \hat{x} \left( \frac{\partial A_s}{\partial y} - \frac{1}{1 + \frac{x}{\rho}} \frac{\partial A_g}{\partial s} \right)$$

$$+ \hat{s} \left( \frac{\partial A_g}{\partial x} - \frac{\partial A_x}{\partial y} \right)$$

rot  $\vec{A}$

$$= \frac{1}{\left(1 + \frac{x}{\rho}\right)} \left[ \frac{\partial \left[ \left(1 + \frac{x}{\rho}\right) A_s \right]}{\partial y} - \frac{\partial A_g}{\partial s} \right] \hat{x}$$

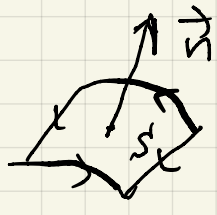
$$+ \frac{1}{\left(1 + \frac{x}{\rho}\right)} \left[ \frac{\partial A_x}{\partial s} - \frac{\partial \left[ \left(1 + \frac{x}{\rho}\right) A_s \right]}{\partial x} \right] \hat{y}$$

$$+ \left( \frac{\partial A_g}{\partial x} - \frac{\partial A_x}{\partial y} \right) \hat{s}$$

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# 別解 Rotation (Vector 回転) とは何か?



$$\lim_{S \rightarrow 0} \left[ \frac{1}{S} \int_{\partial S} \vec{A} \cdot d\vec{r} \right] \vec{n}$$

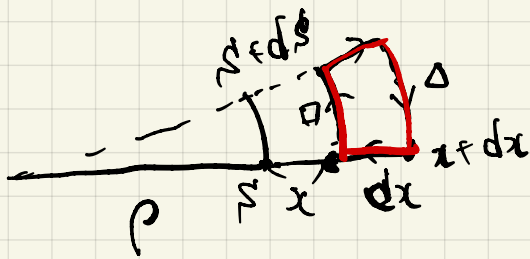
境界

微分係数のことか...  
と思え

Frenet serret

$(s, x)$  座標のとき

$\int ds$



$$\rho: ds = \rho + dx = \square$$

$$\square = \left(1 + \frac{x}{\rho}\right) ds'$$

$$\Delta = \left(1 + \frac{x+dx}{\rho}\right) ds'$$

積分の順序は

$$\square = A_s(x, y, s) \left(1 + \frac{x}{\rho}\right) ds + A_x(x, y, s+ds) dx - A_s(x+dx, y, s+ds) \left(1 + \frac{x+dx}{\rho}\right) ds - A_x(x+dx, y, s) dx$$

$$A_x(x, y, s+ds) = A_x + \frac{\partial A_x}{\partial s} ds$$

$$A_s(x+dx, y, s+ds) = A_s + \frac{\partial A_s}{\partial x} dx + \frac{\partial A_s}{\partial s} ds$$

$$A_x(x+dx, y, s) = A_x + \frac{\partial A_x}{\partial x} dx$$

$$\square = \frac{\partial A_x}{\partial s} dx ds - \frac{\partial A_x}{\partial x} dx dx - \frac{\partial A_s}{\partial x} \left(1 + \frac{x}{\rho}\right) dx ds$$

$$- A_s \frac{1}{\rho} ds dx$$

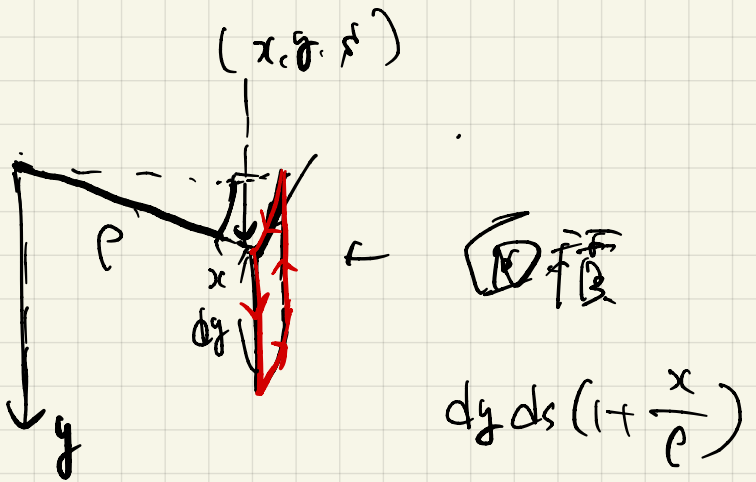
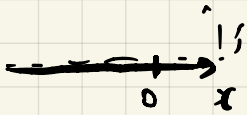
$$- \frac{\partial A_s}{\partial s} \left(1 + \frac{x}{\rho}\right) ds ds$$

$$\text{rot } \vec{A} = \frac{1}{(1 + \frac{x}{\rho})} \left( \frac{\partial A_x}{\partial s} - \frac{A_s}{\rho} - \frac{\partial A_s}{\partial x} \left(1 + \frac{x}{\rho}\right) \right)$$

$$= \frac{1}{1 + \frac{x}{\rho}} \frac{\partial A_x}{\partial x} \frac{dx}{ds} - \frac{\partial A_s}{\partial s} \frac{ds}{dx} \rightarrow 0$$

$$= \frac{1}{(1 + \frac{x}{\rho})} \left( \frac{\partial A_s}{\partial x} - \frac{\partial (1 + \frac{x}{\rho}) A_s}{\partial x} \right) \hat{y} \quad \text{OK}$$

$(y, s)$  平面のとき



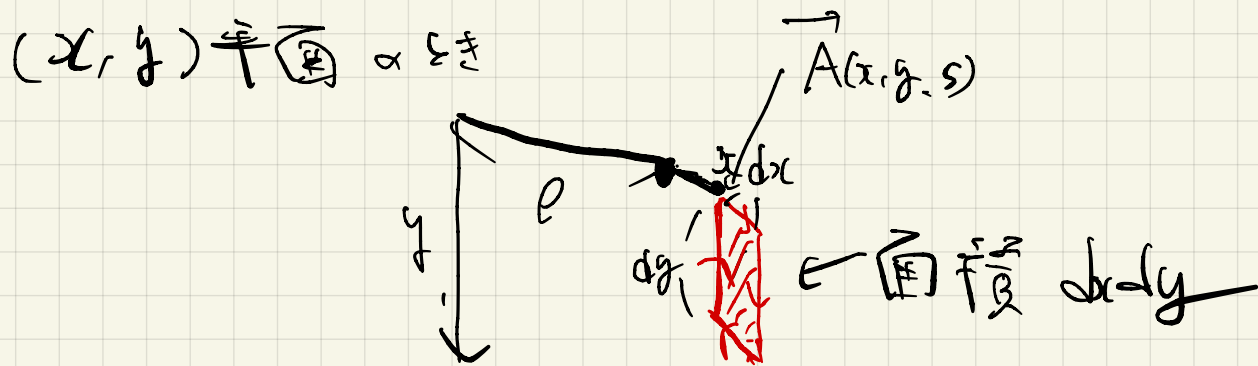
線積分の口

$$\square = A_y(x, y, s) \cdot dy + A_s(x, y + dy, s) \left(1 + \frac{x}{\rho}\right) ds - A_y(x, y + dy, s + ds) dy - A_s(x, y, s + ds) \left(1 + \frac{x}{\rho}\right) ds$$

$dy dy ds ds$  の項は  
消滅する。

$$\square = - \frac{\partial A_y}{\partial s} dy ds + \frac{\partial A_s}{\partial y} \left(1 + \frac{x}{\rho}\right) dy ds$$

$$\text{rot } \vec{A} = \frac{1}{(1 + \frac{x}{\rho})} \left( \frac{\partial (1 + \frac{x}{\rho}) A_s}{\partial y} - \frac{\partial A_y}{\partial s} \right) \hat{x} \quad \text{OK}$$



Σ 面積分 □ 15

$$\square = A_x(x, y, s) dx + A_y(x+dx, y, s) dy - A_x(x+dx, y+dy, s) dx - A_y(x, y+dy, s) dy$$

$$= -\frac{\partial A_x}{\partial y} dx dy + \frac{\partial A_y}{\partial x} dx dy$$

$$\text{rot } \vec{A} = \left( \frac{\partial A_y}{\partial x} - \frac{\partial A_x}{\partial y} \right) \hat{s}$$

$\vec{f} = \rho \vec{z}$ ,  $(-\vec{f} \hat{x})$  ( $=$ )

$$\text{rot } \vec{A} = \frac{1}{\left(1 + \frac{x}{\rho}\right)} \left[ \frac{\partial \left(1 + \frac{x}{\rho}\right) A_s}{\partial y} - \frac{\partial A_y}{\partial s} \right] \hat{x}$$

$$+ \frac{1}{\left(1 + \frac{x}{\rho}\right)} \left[ \frac{\partial A_x}{\partial s} - \frac{\partial \left(1 + \frac{x}{\rho}\right) A_s}{\partial x} \right] \hat{y}$$

$$+ \left( \frac{\partial A_y}{\partial x} - \frac{\partial A_x}{\partial y} \right) \hat{s}$$